

Fig.1

Periodic test-object orientation on the microscope stage.

1. is the microscope frame(field of view);
2. are the diffraction grating strip images.

The arrow at the top of the frame indicates the line scan direction.

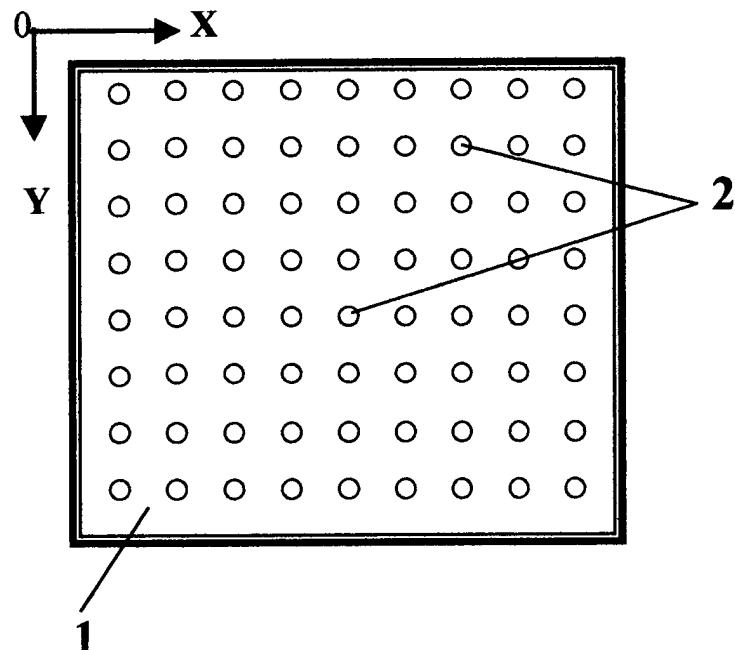


Fig.2

Two-dimensional array of signal values.

1. is the microscope field of view;
2. are the individual signal values at places with coordinates X and Y.

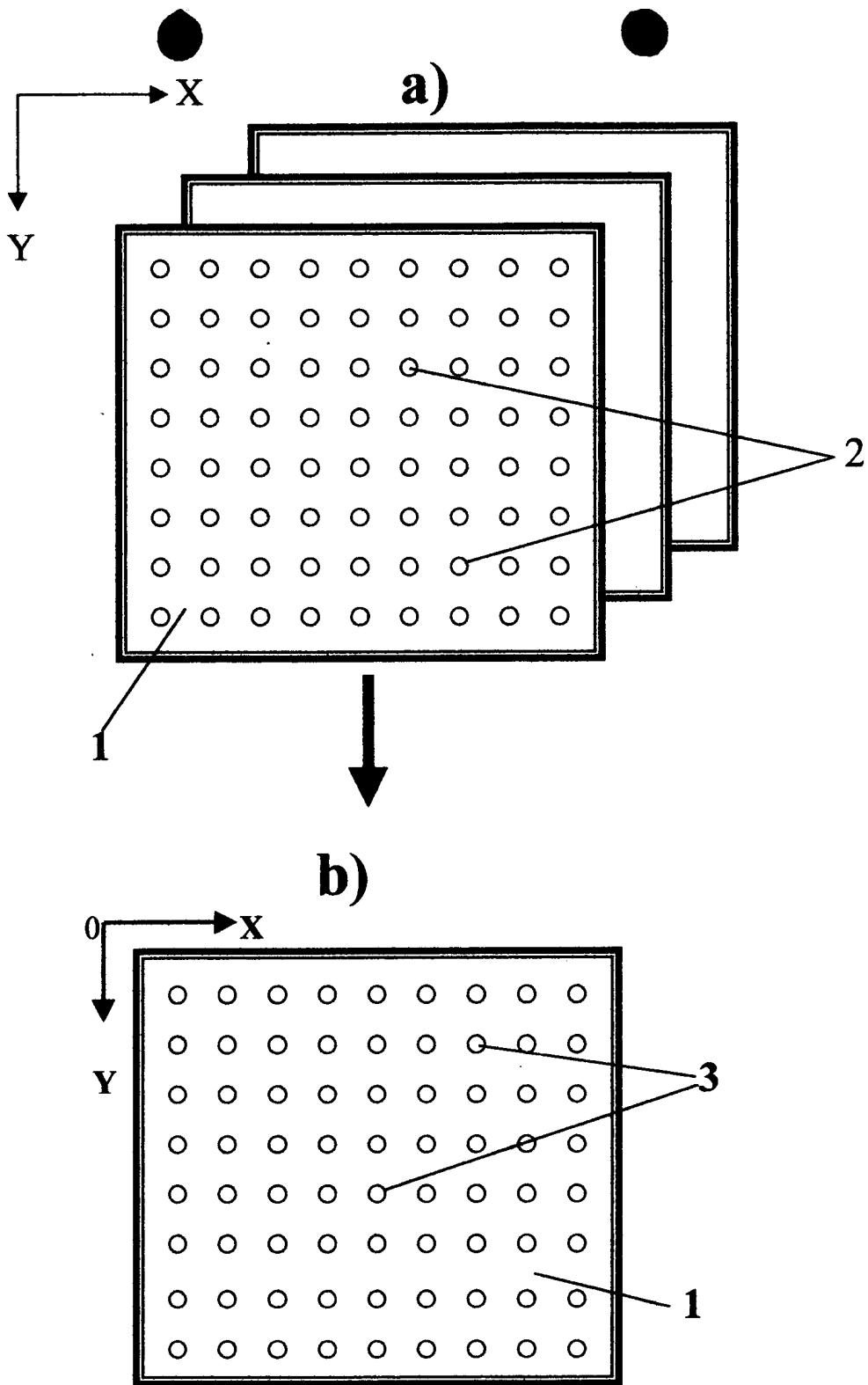


Fig.3
The procedure of arrays averaging.

- a) is the set of initial two-dimensional signal arrays;
- b) is the averaged two-dimensional signal array;

1. is the microscope field of view; 2. are the signal values in the initial two-dimensional arrays; 3. is the signal values in the averaged two-dimensional array.

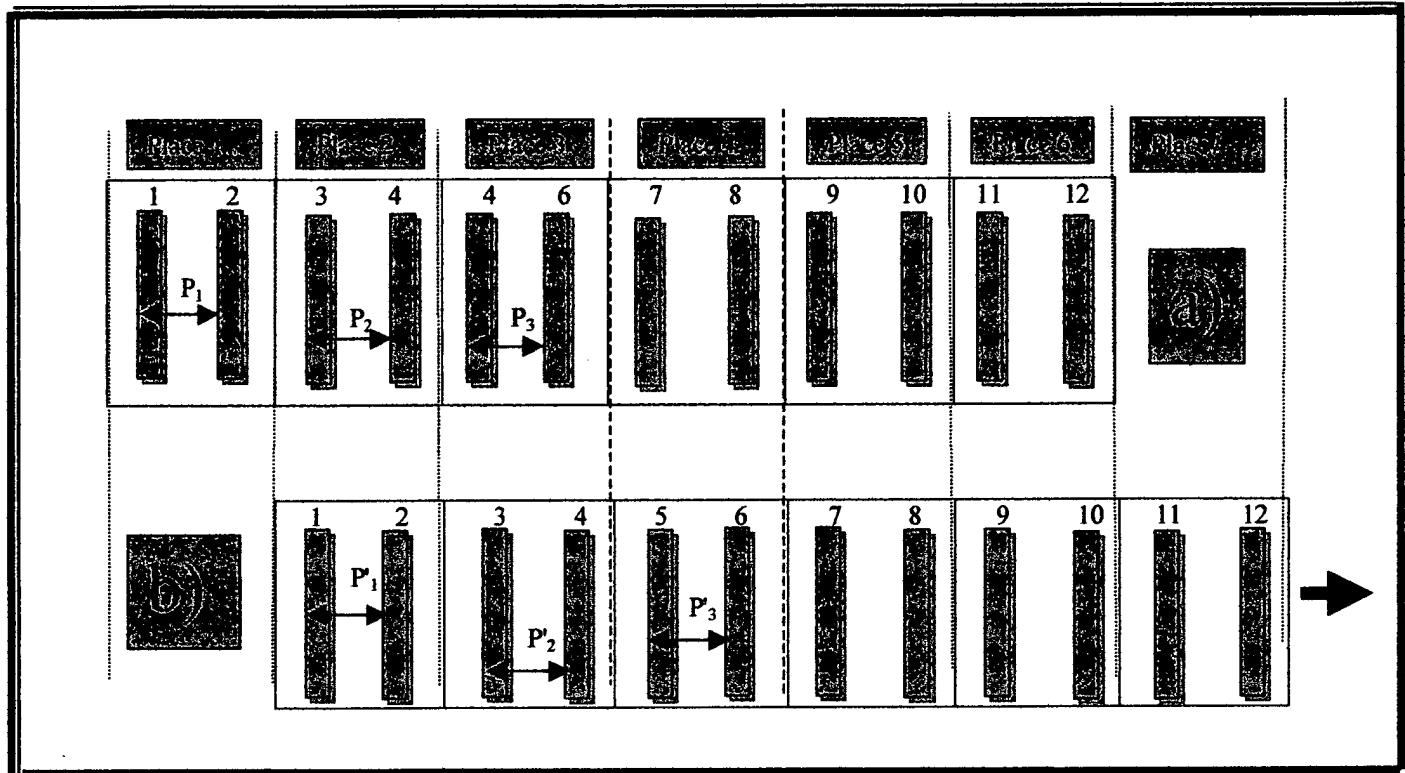


Fig.4

Shift of the diffraction grating image in the microscope field of view
according to Claim 1.e.

Row a) is the initial grating image; row b) is the image of shifted grating.
The arrow at bottom right indicates the shift direction.

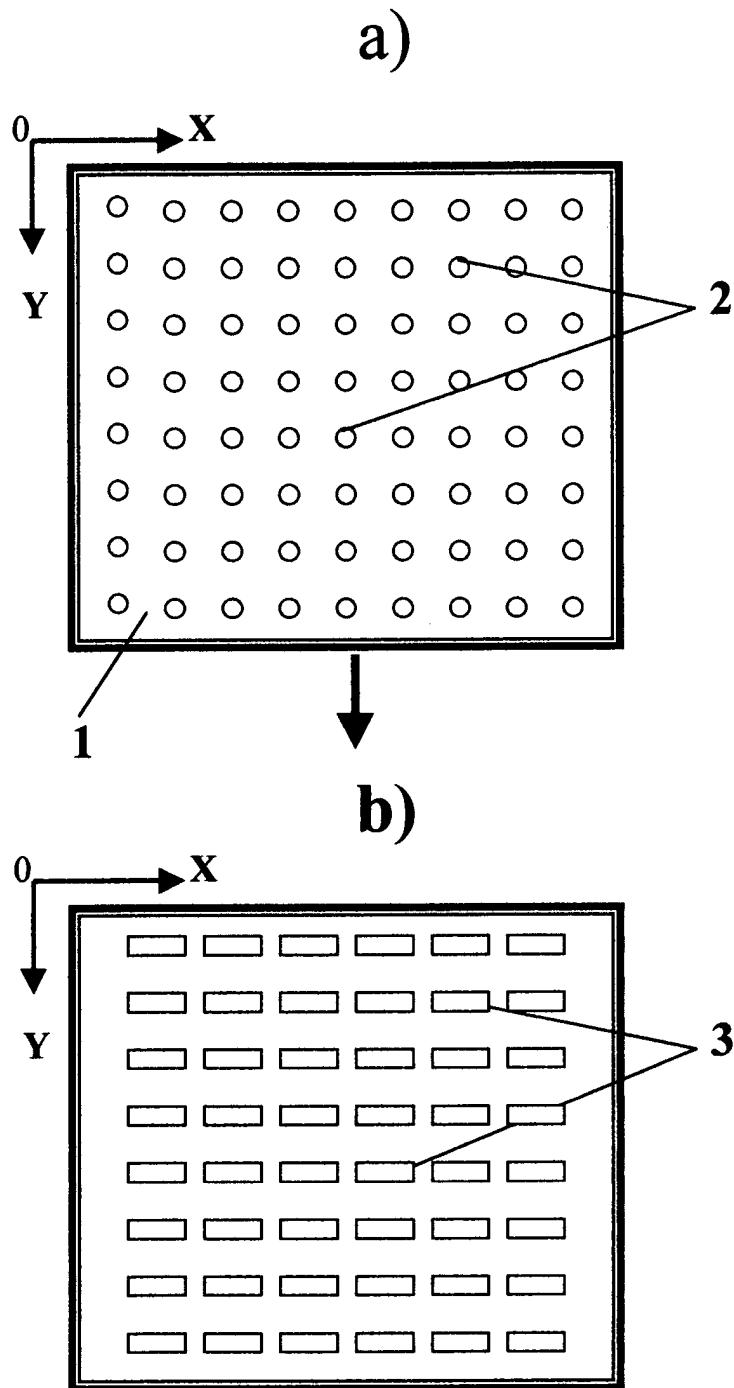
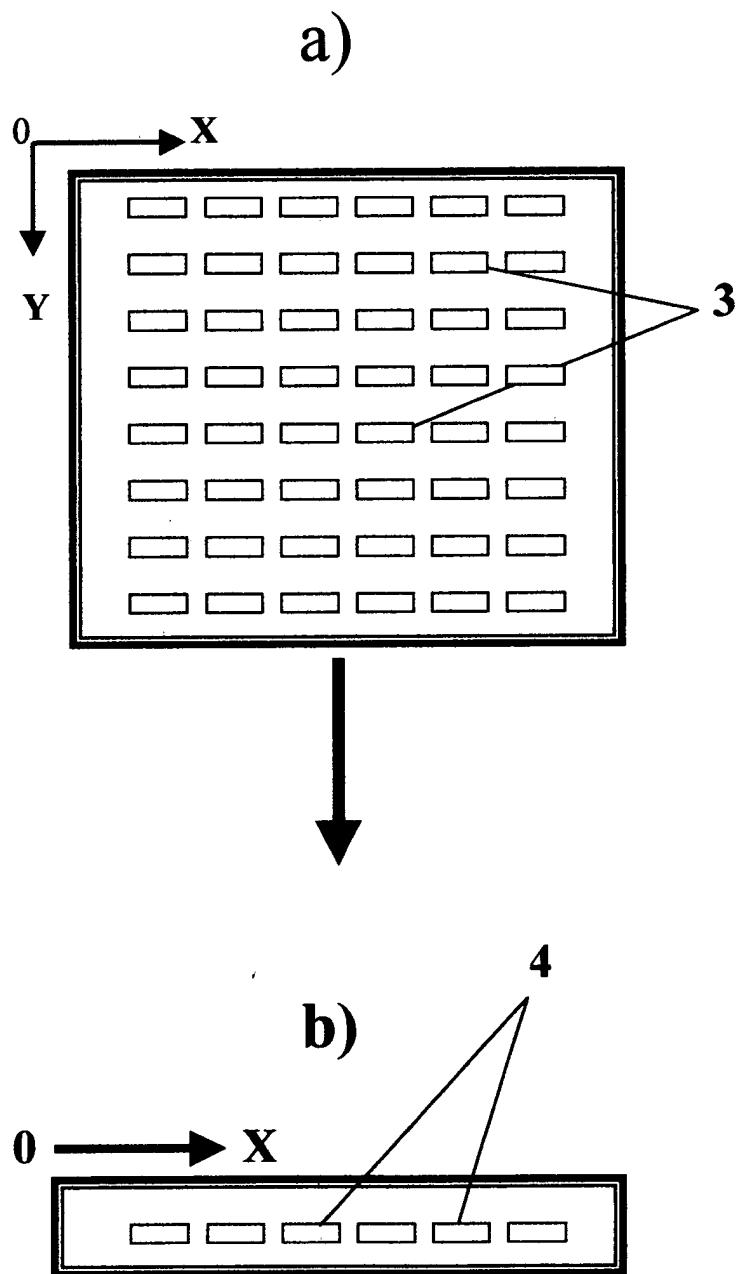


Fig.5

Transformation of two-dimensional individual signal values array (a) into two-dimensional individual pitch values array (b).

1. is the microscope field of view;
2. are the individual signal values; 3. are the individual pitch values.

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Fig.6
Transformation of the two-dimensional individual pitch values array (a)
into one-dimensional mean pitch values profile (b).

3. are the individual pitch values;
4. is the mean pitch values profile obtained by averaging
of individual pitch values along Y-direction.

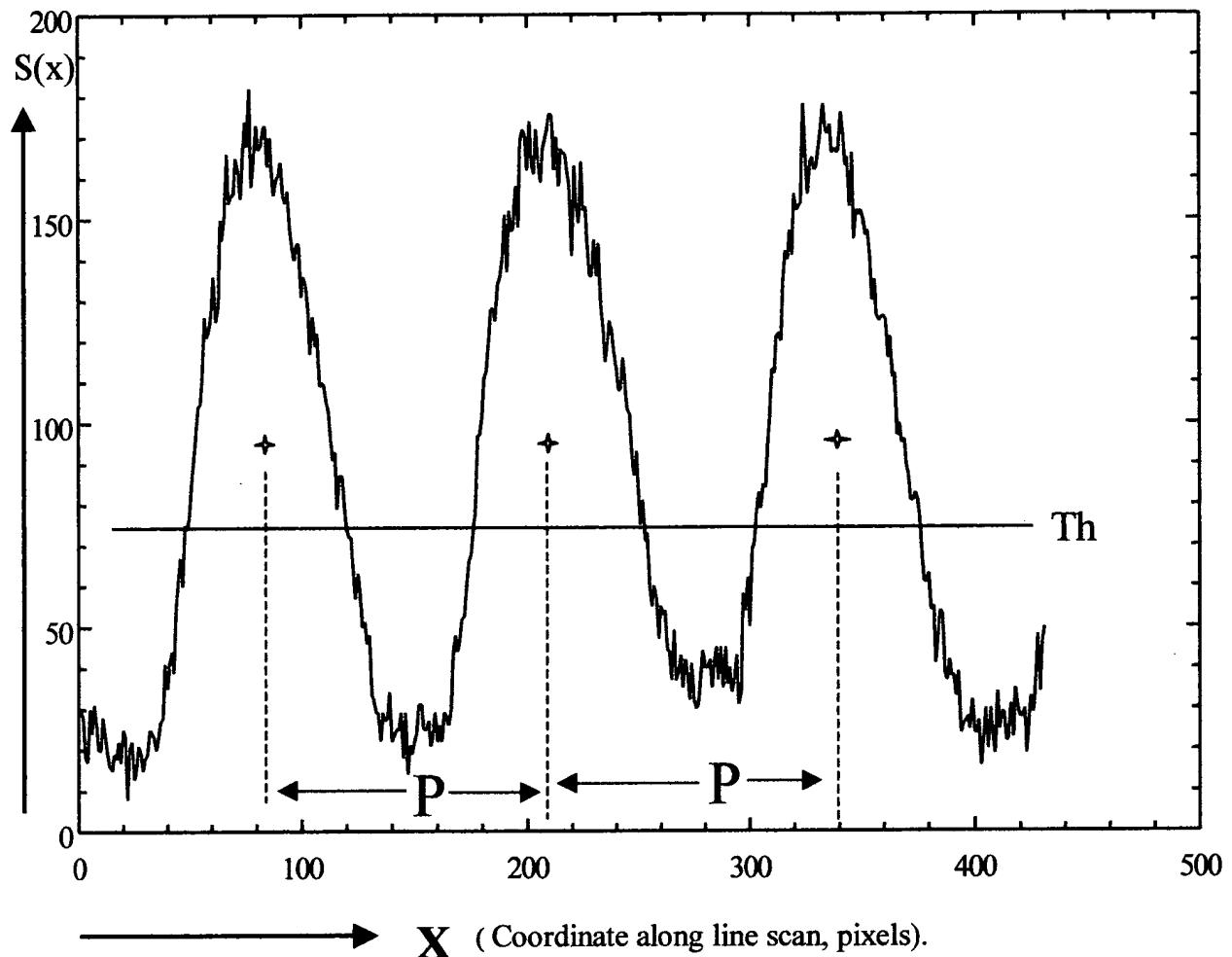


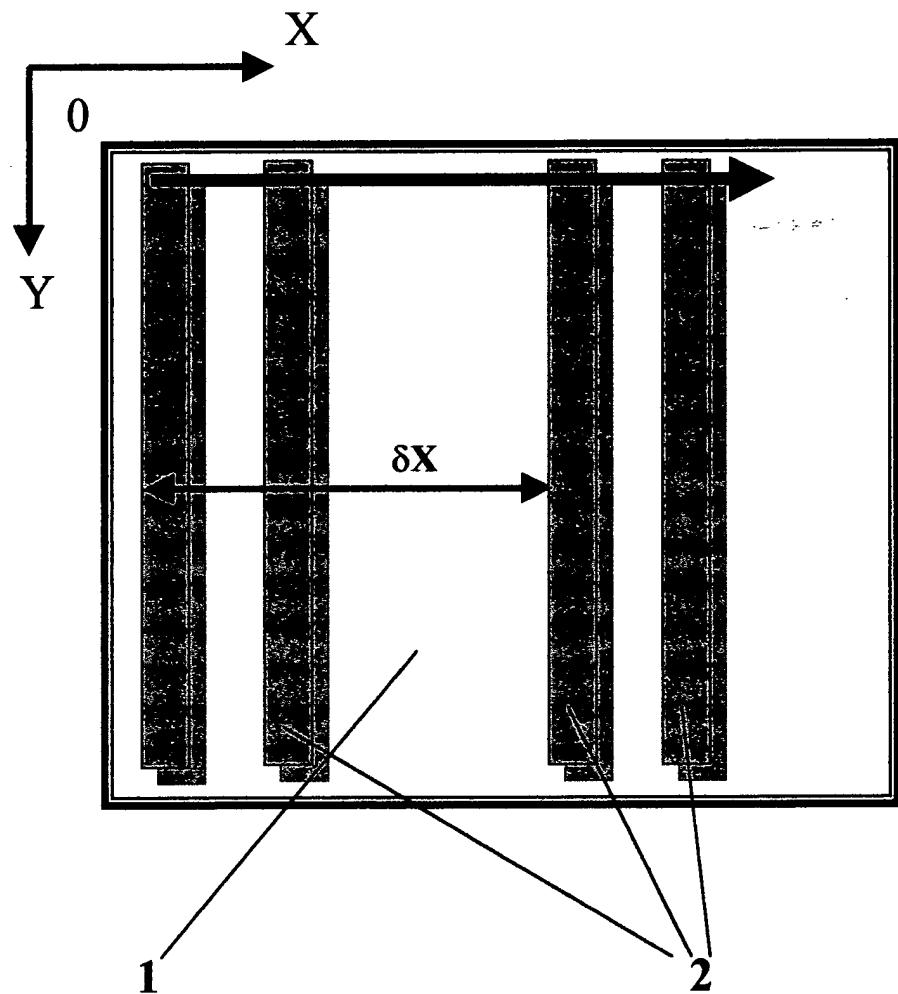
Fig.7

Signal cutting off by threshold (Th).

The solid curve represents the dependence of video-signal $S(x)$ plotted against coordinate X along line scan.

The sign \oplus indicates the position of the Centres of mass of signal "islands".

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Fig.8

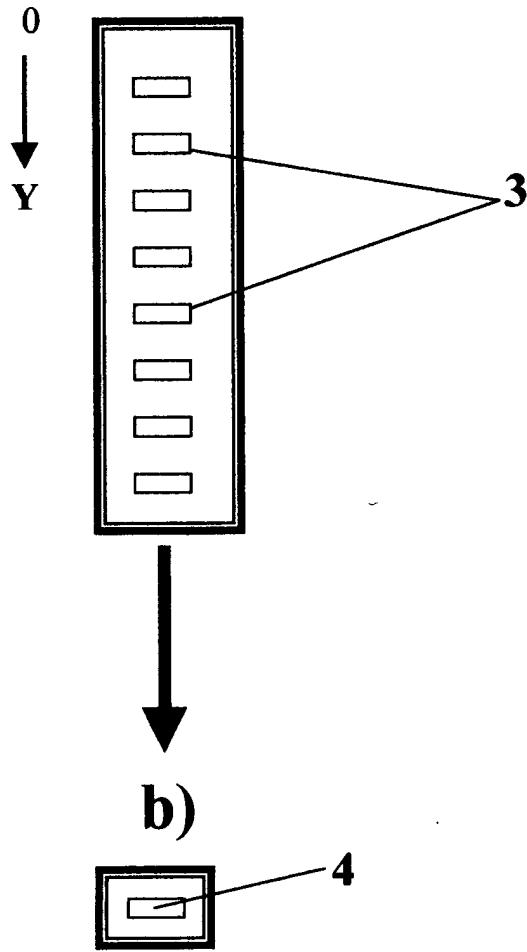
**Shift of the strip pair across microscope field of view
according to Claim 7.**

The arrow at the top of frame indicates the shift direction; the arrow at the frame middle indicates the shift magnitude δX .

1 is the microscope frame(field of view);
2 are the test-object strips images.



a)

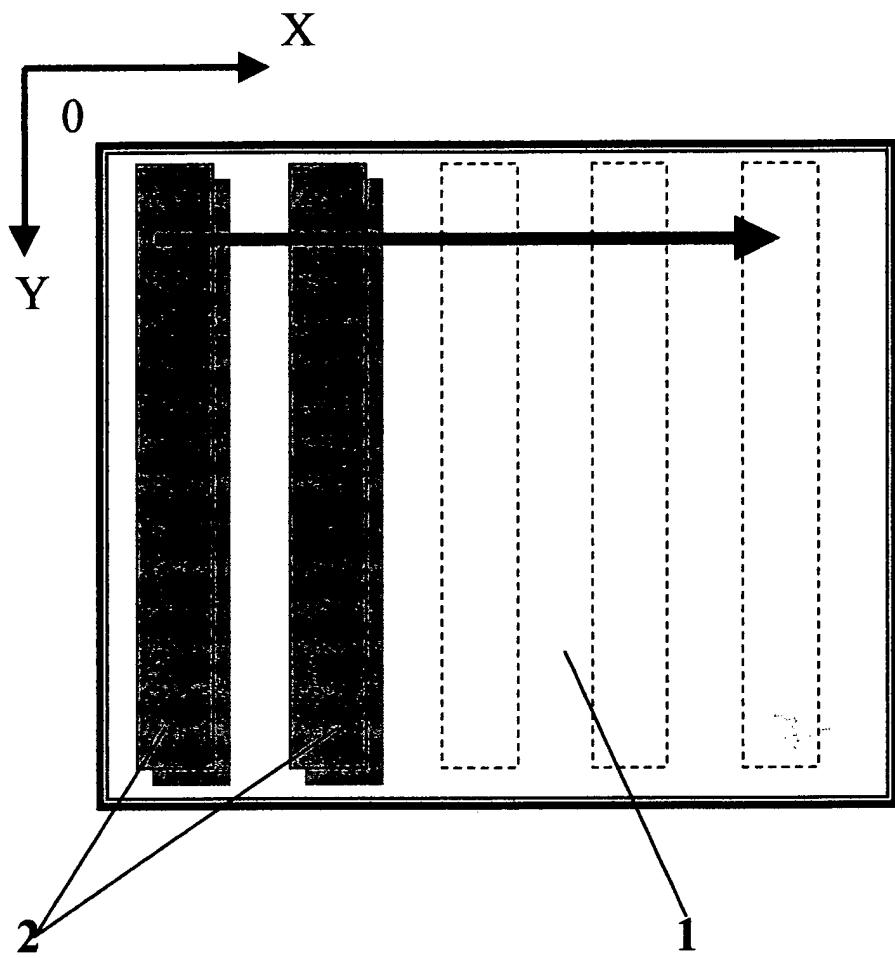


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Fig.9

Transformation of the one-dimensional individual pitch values array (a) into mean pitch value (b) according to Claims 5d and 5h.

3. are the individual pitch values versus coordinate Y; 4. is the mean pitch value obtained by averaging of individual pitch values along Y-direction.



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Fig.10

Test-object geometry according Claim 7 and its orientation on the microscope stage.

1 is the microscope frame (field of view);

2 are the test-object strips images.

The arrow at top of the frame indicates the line scan direction.

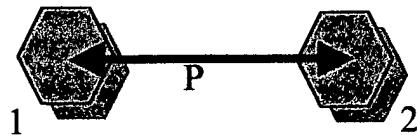
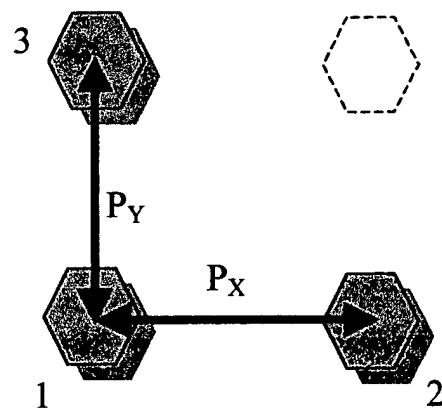


Fig.11

Geometry of the test-object according Claim 10.

P is the distance between features 1 and 2 i.e. pitch value.



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Fig.12

Geometry of the test-object according Claim 11.

P_x is the distance between features 1 and 2 i.e. the pitch value along X-axis; P_y is the distance between features 1 and 3 i.e. the pitch value along Y-axis.

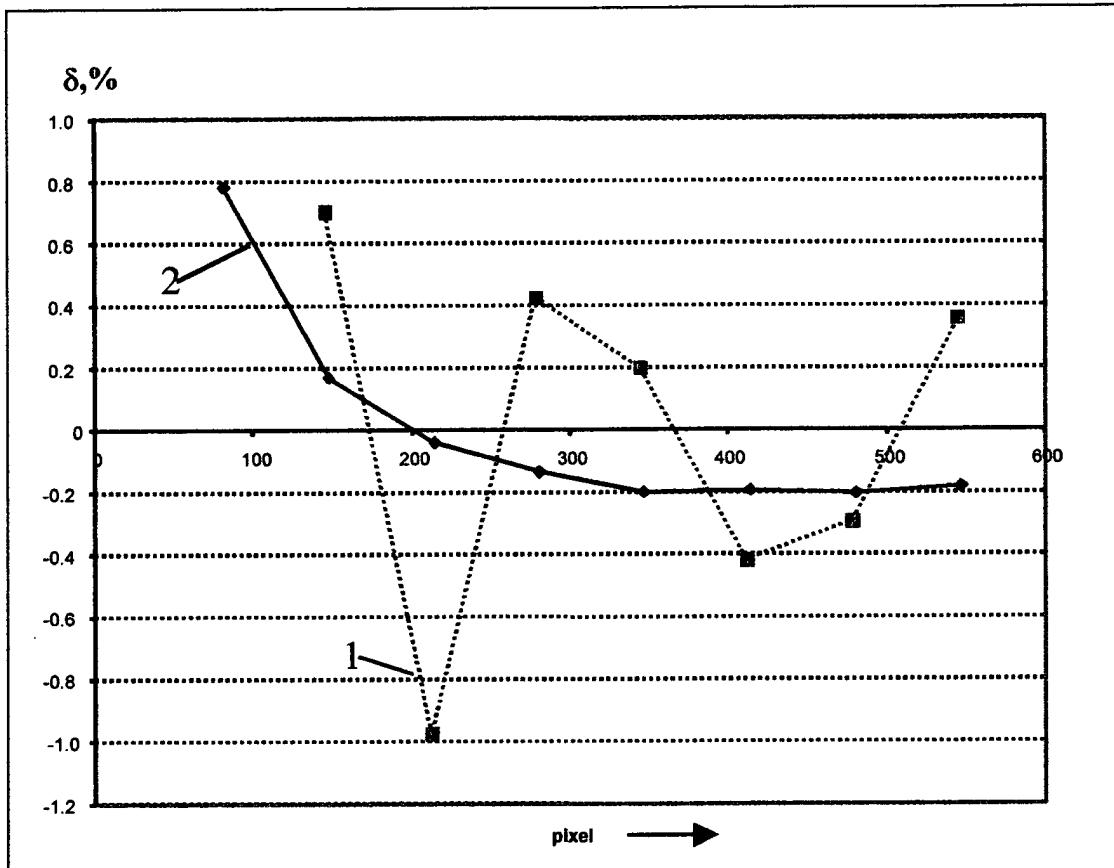


Fig.13.

The comparison of apparent (1) and true (2) scan non-linearity of the attested SEM. The tar δ (percents) plotted along Y is showing how much real local magnification differs from average one.

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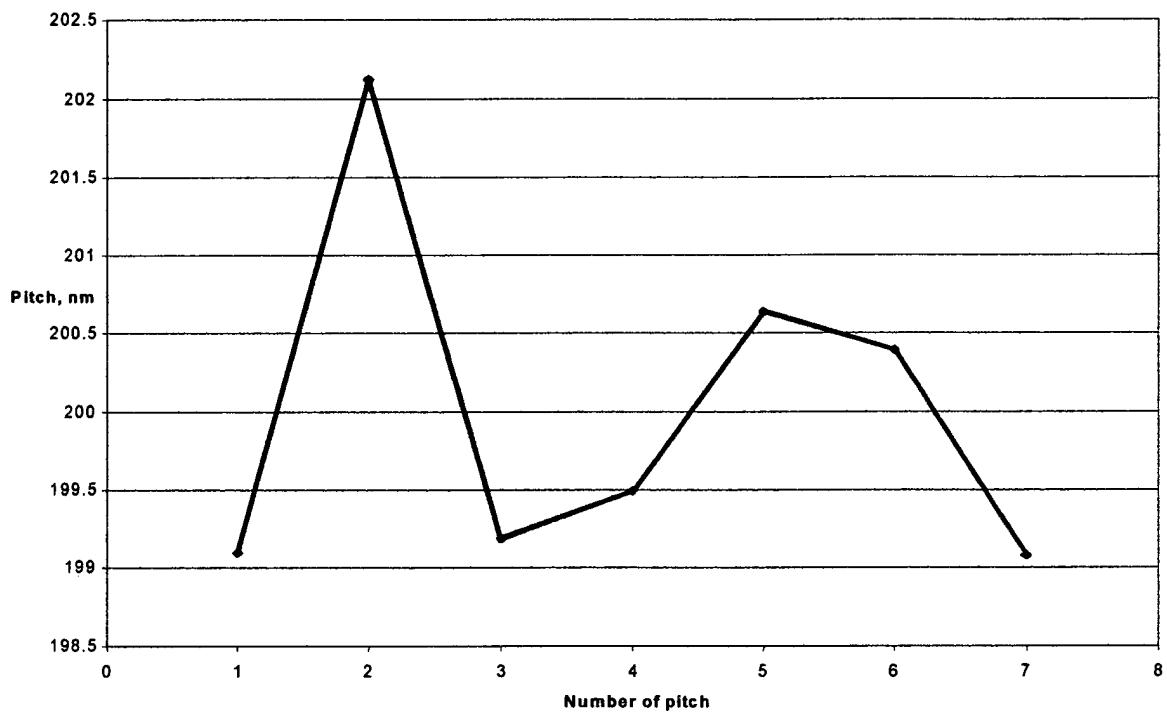


Fig.14.
The Sample non-uniformity